

# EFFICIENT NONMYOPIC ACTIVE SEARCH

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# 1. ACTIVE SEARCH

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Finding interesting points

# Active search<sup>1</sup>

- In *active search*, we consider active learning with an unusual goal: *locating as many members of a particular class as possible*.
- Numerous real-world examples:
  - drug discovery,
  - intelligence analysis,
  - product recommendation,
  - playing Battleship.

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<sup>1</sup>Garnett, Krishnamurthy, Xiong, Schneider (CMU), Mann (Uppsala).  
ICML 2012.

# Battleship!



# Another definition

Active search is Bayesian optimization with *binary rewards* and *cumulative regret*.

# Our approach

We approach this problem via *Bayesian decision theory*.

- We define a natural *utility function*, and
- The location of the next evaluation will be chosen by *maximizing the expected utility*.

# The utility function (cumulative reward)

The natural utility function for this problem is *the number of interesting points found*.

# The Bayesian optimal policy

The optimal policy may be derived by sequentially maximizing the expected utility of the *final dataset*. With a budget of  $B$ , at time  $t$ , we select

$$\begin{aligned} & \arg \max_{x_t} \mathbb{E}[u(\mathcal{D}_B) \mid x_t, \mathcal{D}_{t-1}] \\ &= \arg \max_{x_t} [\text{expected utility starting from point } x_t]. \end{aligned}$$



# The Bayesian optimal policy

This may be written *recursively*:

$$\begin{aligned} \text{[expected utility starting from point]} = & \\ & \text{[current utility]} + \\ & \underbrace{\text{[expected utility of point]} +}_{\text{exploitation, } < 1} \\ & \underbrace{\mathbb{E}_{y_t} \left[ \text{[success of remaining search]} \right]}_{\text{exploration, } < B-t}. \end{aligned}$$

Automatic *dynamic* tradeoff between exploration and exploitation!

# Lookahead

- Unfortunately, the computational cost of computing the optimal policy is *expensive*. (Exponential in the number of points!)
- In practice, we use a *myopic approximation*, where we effectively pretend there is only a small number of observations remaining.

# The Bayesian optimal policy

$$\begin{aligned} \text{[expected utility starting from point]} = & \\ & \text{[current utility]} + \\ & \underbrace{\text{[expected utility of point]} +}_{\text{exploitation, } < 1} \\ & \underbrace{\mathbb{E}_{y_t} \left[ \text{[success of remaining search]} \right]}_{\text{exploration, } < B-t}. \end{aligned}$$

# $\ell$ -step myopic approximation

$$\begin{aligned} \text{[expected utility of next few points]} = & \\ & \text{[current utility]} + \\ & \underbrace{\text{[expected utility of point]} +}_{\text{exploitation, } < 1} \\ & \underbrace{\mathbb{E}_{y_t} \left[ \text{[success of next few points]} \right]}_{\text{exploration, } < \ell}. \end{aligned}$$

( $\ell$  is normally 2–3).

# Problems

- The dependence on the budget has been *lost!*
- Exploration is heavily *undervalued!*

# Lookahead can always help

**Theorem** (Garnett, et al.)

Let  $\ell, m \in \mathbb{N}^+$ ,  $\ell < m$ . For any  $q > 0$ , there exists a search problem  $\mathcal{P}$  such that

$$\frac{\mathbb{E}_{\mathcal{D}}[u(\mathcal{D}) \mid m, \mathcal{P}]}{\mathbb{E}_{\mathcal{D}}[u(\mathcal{D}) \mid \ell, \mathcal{P}]} > q;$$

that is, the  $m$ -step active-search policy can outperform the  $\ell$ -step policy by any arbitrary degree.

# Our idea: Efficient nonmyopic active search

- Our idea is to approximate the remainder of the search differently. We assume that any remaining budget is selected *simultaneously in one big batch*.
- Similar idea to the GLASSES algorithm, in a different context (and in this case, *exact* and *efficient*).
- Exploration encouraged *correctly!* Automatic, *dynamic* tradeoff restored!

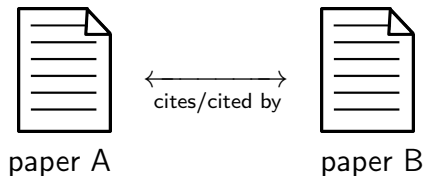
## 2. QUICK EXPERIMENT

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# CiteSeer data

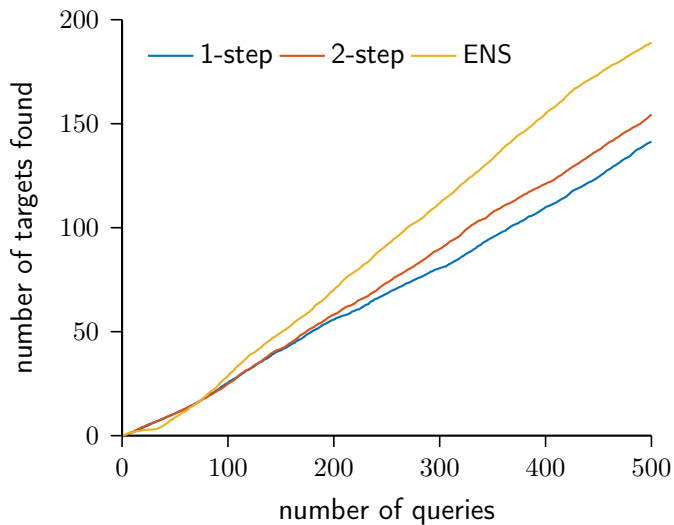
- Includes papers from the 50 most popular venues present in the CiteSeer database.
- 42k nodes, 222k edges.
- We search for *NIPS* papers, 2.5k papers (6%).



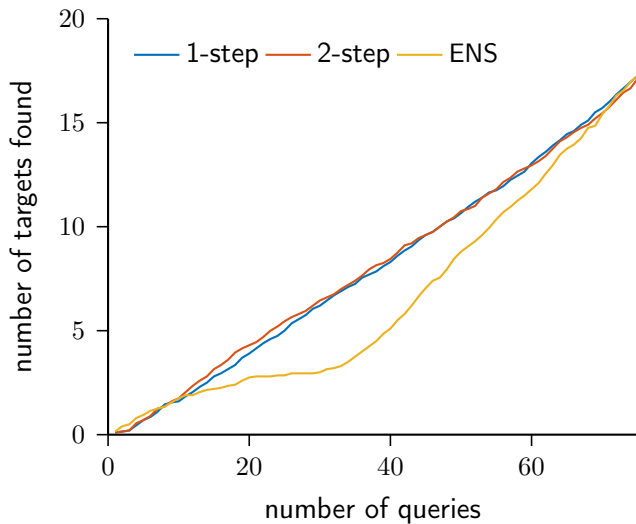
# Experiment

- We select a single NIPS paper at random, and begin with that single positive observation.
- The one- and two-step myopic approximations were compared with our method (ENS).

# Results



# Results: Zoom



# Results: Budget

policy	query number				
	100	300	500	700	900
one-step	25.5	80.5	141	209	273
two-step	24.9	89.8	155	220	287
ENS-900	25.9	94.3	163	239	<b>308</b>
ENS-700	28.0	105	188	<b>259</b>	
ENS-500	28.7	<b>112</b>	<b>189</b>		
ENS-300	26.4	105			
ENS-100	<b>30.7</b>				

## 2. THANK YOU!

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Questions?